
Learning big logical rules by joining small rules

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Inductive Logic Programming (ILP)

a form of program synthesis

Inductive Logic Programming (ILP)

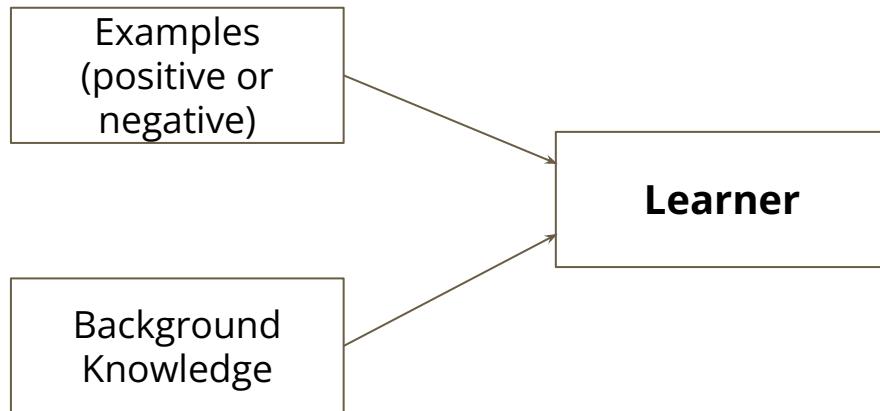
Examples
(positive or
negative)

Inductive Logic Programming (ILP)

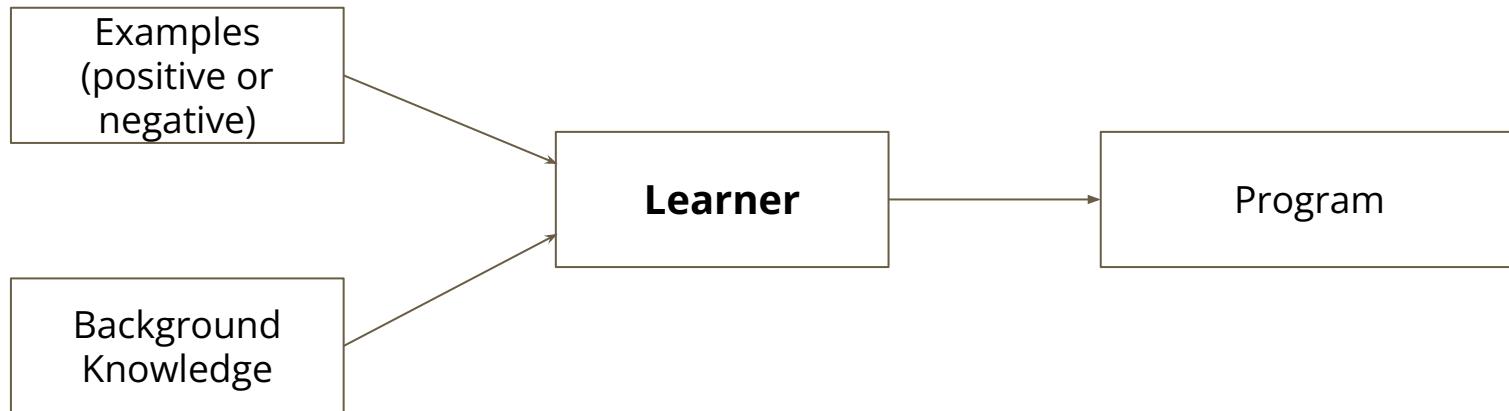
Examples
(positive or
negative)

Background
Knowledge

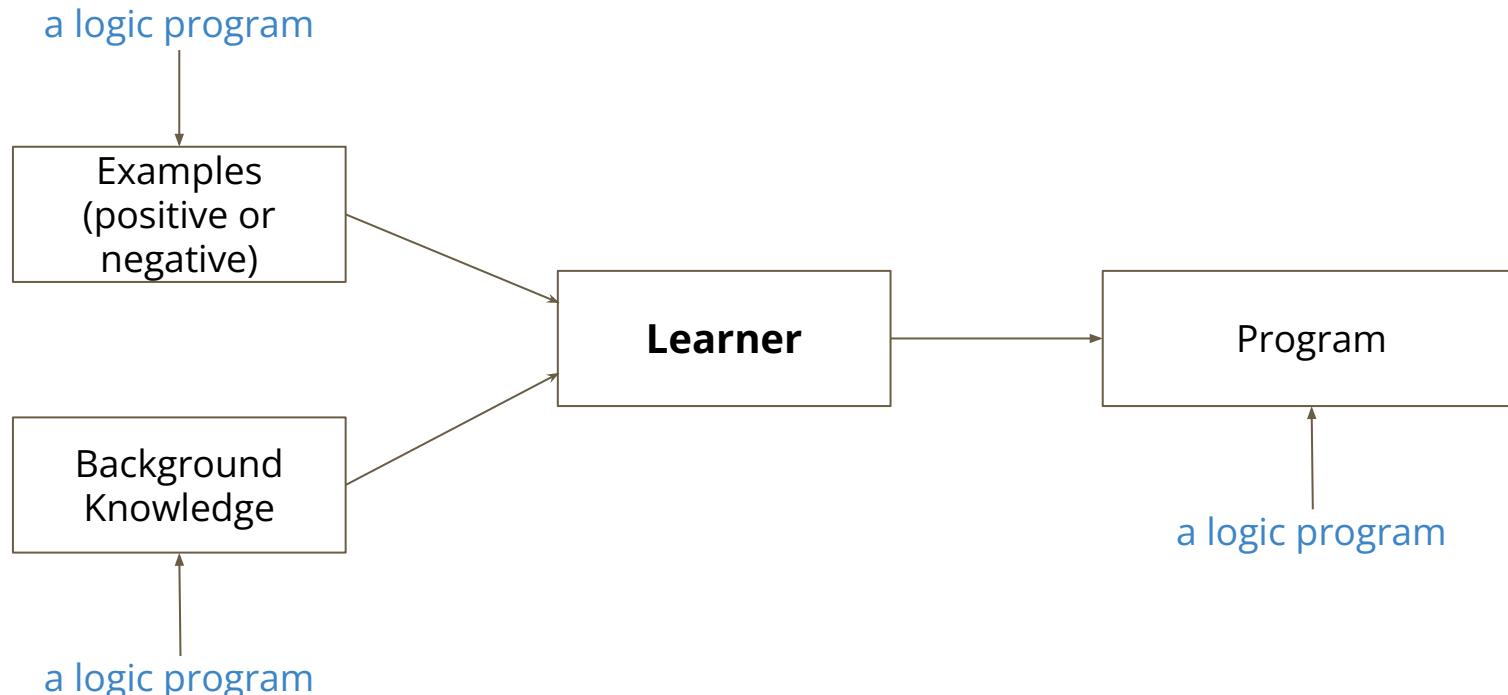
Inductive Logic Programming (ILP)

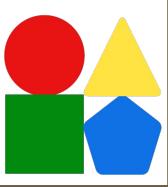
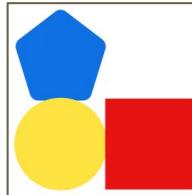
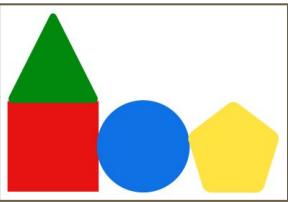
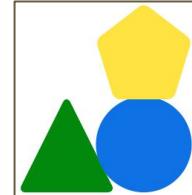
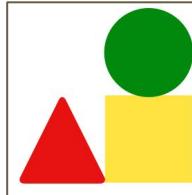


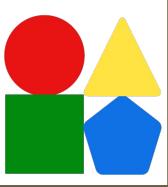
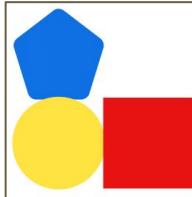
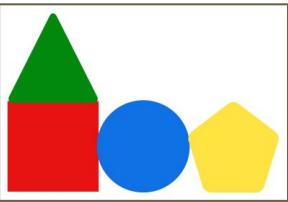
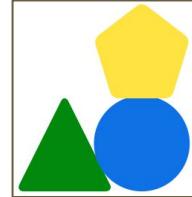
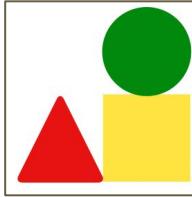
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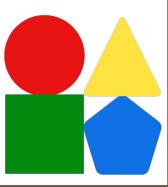
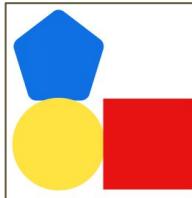
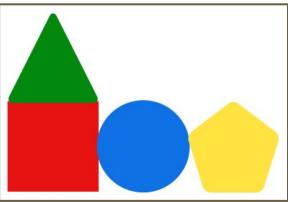
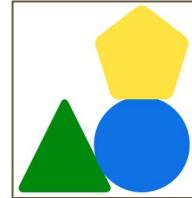
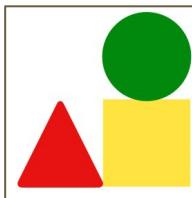
Inductive Logic Programming (ILP)



Positive examples	Negative examples
	
	 

Positive examples	Negative examples
	
	 

Background Knowledge	
<p>piece(ex1,p1_1). red(p1_1). square(p1_1). piece(ex1,p1_2). green(p1_2).</p>	<p>piece(ex2,p2_1). green(p2_1). triangle(p2_1). piece(ex2,p2_2). red(p2_2).</p>

Positive examples	Negative examples
	
	 

Background Knowledge	
<code>piece(ex1,p1_1).</code>	<code>piece(ex2,p2_1).</code>
<code>red(p1_1).</code>	<code>green(p2_1).</code>
<code>square(p1_1).</code>	<code>triangle(p2_1).</code>
<code>piece(ex1,p1_2).</code>	<code>piece(ex2,p2_2).</code>
<code>green(p1_2).</code>	<code>red(p2_2).</code>

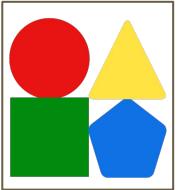
Program
<pre> zendo(Structure) ← piece(Structure,Red), red(Red), piece(Structure,Blue), blue(Blue), piece(Structure,Green), green(Green) </pre>

Challenge

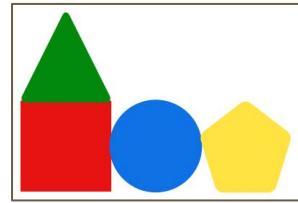
Learning programs with large rules is difficult.

In this work: an approach to learn large rules.

Our idea



1. We learn rules which entail some positive examples.



```
zendo1(Structure) ← piece(Structure,Red), red(Red).
```

```
zendo2(Structure) ← piece(Structure,Blue), blue(Blue).
```

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zendo3(Structure) ← piece(Structure,Green), green(Green).
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```
zendo4(Structure) ← piece(Structure,Yellow), yellow(Yellow).
```

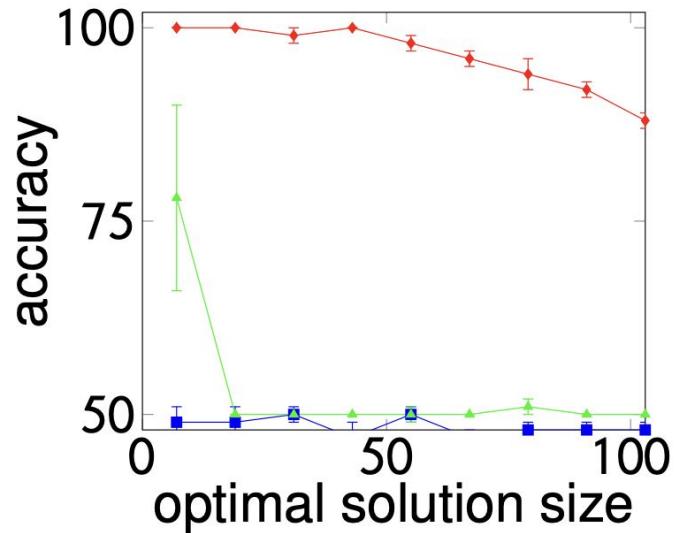
Our idea

1. We learn rules which entail some positive examples.
2. We join rules.

`zendo(Structure) ← zendo1(Structure), zendo2(Structure), zendo3(Structure).`

We implement our approach using a SAT-based approach.

Impact



Our approach can learn rules 10 times longer than current approaches.

Thank you!

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